

Department Elective with Laboratory:

NIRMA UNIVERSITY

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| Institute: | Institute of Technology |
| Name of Programme: | B. Tech in Electronics and Instrumentation Engineering |
| Course Code: | 2EIDE61 |
| Course Title: | Deep learning for vision systems |
| Course Type: | (<input type="checkbox"/> Core/ <input type="checkbox"/> Value Added Course/ <input checked="" type="checkbox"/> Departmental Elective / <input type="checkbox"/> Institute Elective/ <input type="checkbox"/> University Elective/ <input type="checkbox"/> Any other) |
| Year of introduction: | 2023-2024 |

Credit Scheme

| L | T | Practical component | | | C |
|---|---|---------------------|----|-----|---|
| | | LPW | PW | W S | |
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Course Learning Outcomes (CLO):

At the end of the course, students will be able to –

1. illustrate basic architecture of convolution neural networks
2. evaluate existing practical vision systems
3. optimize convolutional neural network model
4. design deep learning based real life vision applications

Syllabus:

Total Teaching hours: 30

| Unit | Syllabus | Teaching hours |
|----------|--|----------------|
| Unit-I | Introduction to computer vision Image acquisition, image pre-processing, feature extraction, computer vision pipeline, applications of computer vision | 04 |
| Unit-II | Deep learning Single layer perceptron, multi-layer perceptron (MLP), activation functions, errors functions, backpropagation, feedforward process, optimization algorithm | 05 |
| Unit-III | Convolutional neural networks Image classifications using MLP, basic components of a convolutional neural network (CNN), CNN architecture, image classification using CNN, overfitting and underfitting, popular CNN architectures | 05 |

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| Unit-IV | Design of deep learning structure Baseline model design, define performance metrics, data preparation, model training, model evaluation, performance estimation, network improvements, hyperparameter tuning, optimization and learning, regularization, batch normalization | 09 |
| Unit-V | Image classifications Object detection, transfer learning, object classification, advanced CNN architectures | 07 |
| Self-Study: | The self study contents will be declared at the commencement of semester. Around 10% of the questions will be asked from self study contents. | |
| Laboratory Work: | Laboratory Work will consist of minimum 10 experiments based on the above syllabus. | |
| Suggested List of Experiments: | <ol style="list-style-type: none"> 1. Introduction to the simulation software 2. Image pre-processing and feature extraction 3. Apprehend the activation functions and error functions 4. Apply the feedforward and backpropagation learning 5. Image data preparation 6. Model training 7. Perform model optimization and evaluation 8. Model improvements and hyperparameter tuning 9. Apply regularization and batch normalization 10. Design of an object detection application 11. Design of an object classification application 12. Understand advanced CNN architecture | |
| Suggested Readings/References: | <ol style="list-style-type: none"> 6. Mohamed elgendy, Deep learning for vision systems, Manning publications 7. Ian Goodfellow, Yoshua Bengio, Aaron Courville, Deep learning, The MIT press publications 8. Francois chollet, Deep learning with python, Manning publications 9. Josh patterson, Adam gibson, Deep learning: A practitioner's approach, Shroff/O'Reilly publications 10. Nikhil buduma, Nicholas locascio, Fundamentals of deep learning: Designing next-generation machine intelligence algorithms, Shroff/O'Reilly publications | |
| Suggested Case List: | Fabric defect detection, empty bottle inspection, sorting/grading applications, surface defect detection applications, print quality inspection etc. | |

L= Lecture, T=Tutorial, P= Practical, C= Credit

w.e.f. academic year 2023-24 and onwards.

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